

# Lunar Lander

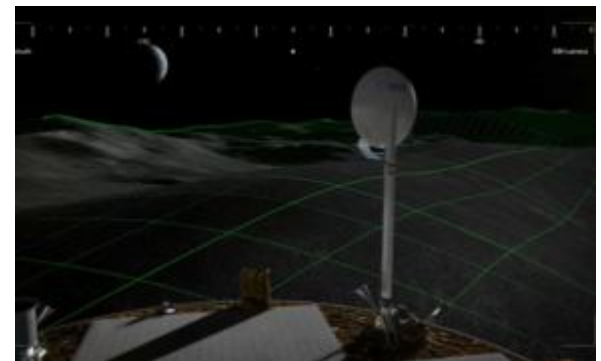
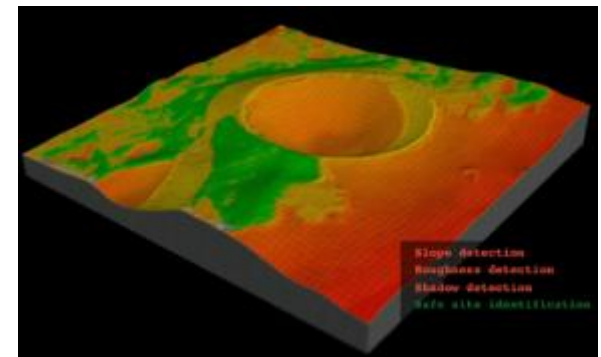
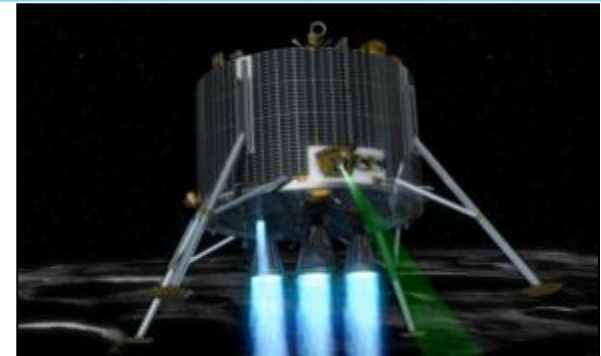


ESA Thematic information day  
BELSPO, 3 July 2012

**TECHNOLOGICAL OBJECTIVE**, preparing for future robotic and human exploration missions:

- **PRECISION LANDING** with surface hazard avoidance, based on Visual Navigation and advanced Guidance Navigation and Control
- **AUTONOMOUS** on board decision during crucial landing phase
- **Energy efficient** design, based on solar energy for surface operation

**SCIENTIFIC investigations** of the Moon surface environment, its effects and potential resources.





# International Context

## Apollo/Luna Era

## 1990 - 2006

- HITEN 
- CLEMENTINE 
- LUNAR PROSPECTOR 
- SMART-1 

## 2007 - 2012

- KAGUYA 
- L-CROSS 
- LRO 
- GRAIL 
- ARTEMIS 
- CHANG'E-1 
- CHANG'E-2 
- CHANDRAYAAN-1 

## 2013 - 2020

- SELENE-2 
- LADEE 
- GOOGLE-X 
- LUNAR LANDER 
- CHANG'E-3 
- CHANG'E-4 
- CHANDRAYAAN-2/  
LUNAR-RESOURCE 
- CHANDRAYAAN-3 
- LUNA-GLOB 

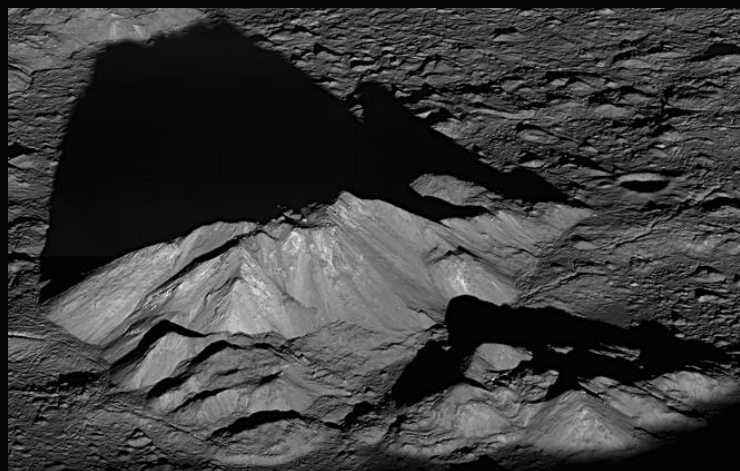
## Next Decade

HUMAN LUNAR  
EXPLORATION  
MISSIONS

LUNAR POLAR  
SAMPLE RETURN

LUNAR  
GEOPHYSICAL  
NETWORK

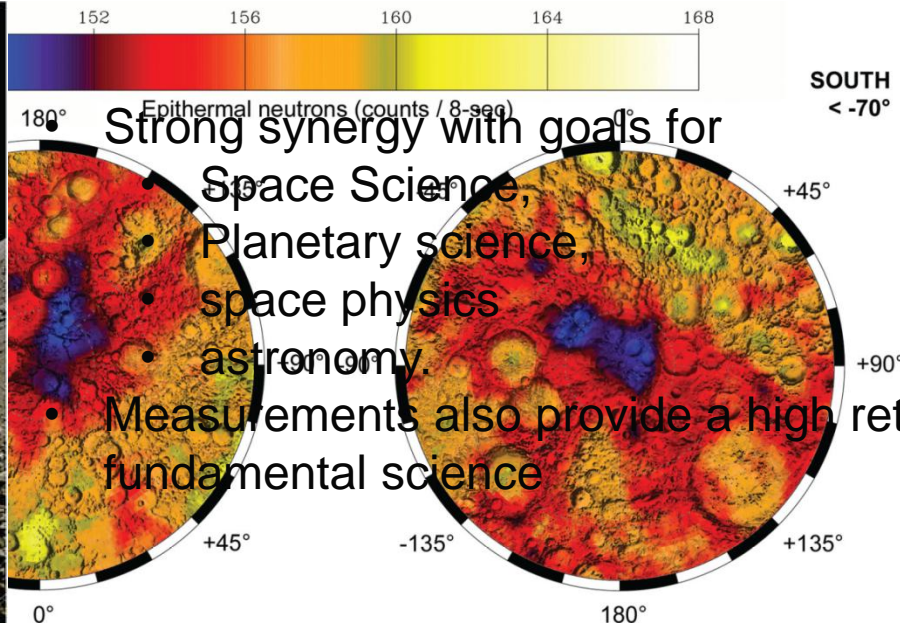
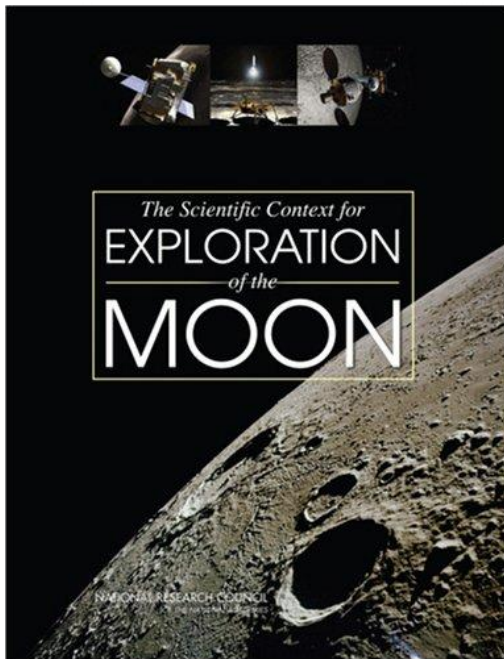
- ORBITER
- IMPACTOR
- LANDER
- SAMPLE RETURN





# Science Objectives

Research Area	Investigation Topic
Human health	Toxicity of lunar dust associated risks to humans
	Radiation environment and likely hazards to humans
Environment and effects	Landing site characterization
	Dust properties and effects on systems
	Dust - Plasma environment and effects
Resources	water, other volatiles and mineralogical species
	Physical properties of potential resources
Preparations for future activities	Characterize the exosphere
	Radio astronomy precursor measurements

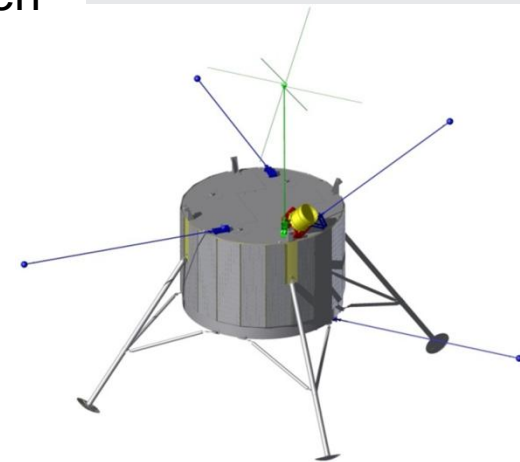
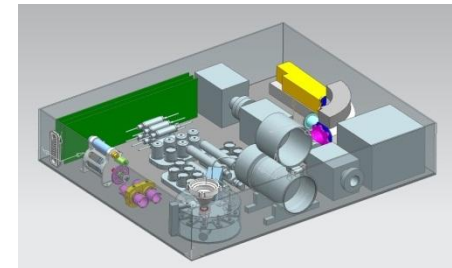
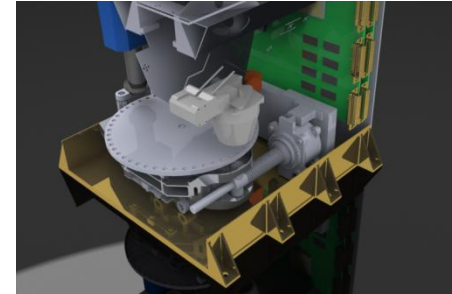


- Strong synergy with goals for Space Science, Planetary science, space physics, astronomy.
- Measurements also provide a high return for fundamental science

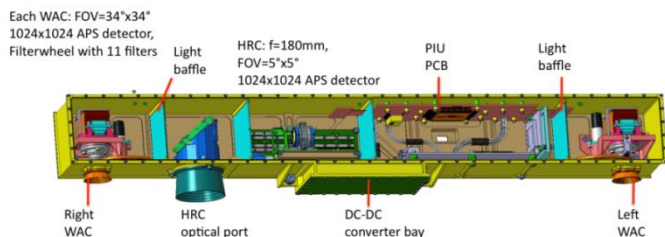
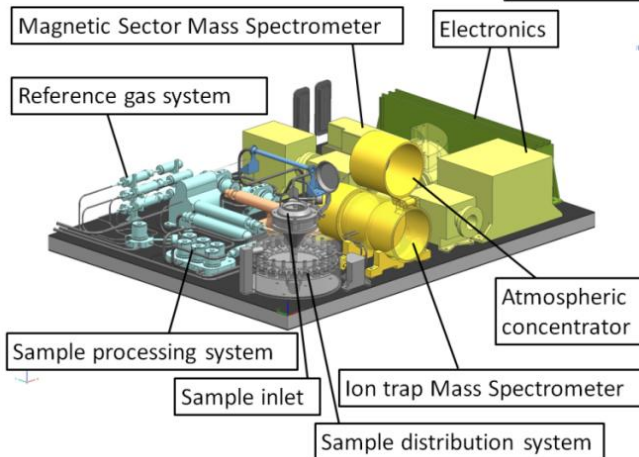
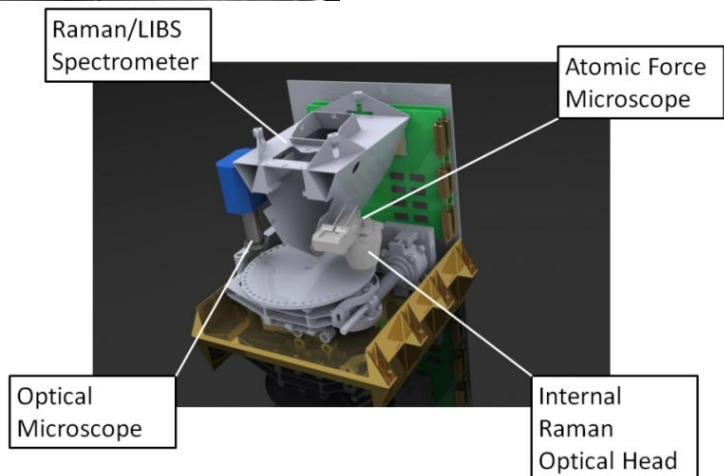
# Payload Definition Studies

- 6 x GSP Payload definition studies ongoing
  - **L-DAP**: dust analysis package investigating size distribution, structure and morphology of lunar dust, plus its chemistry, mineralogy and elemental composition
  - **L-VRAP**: volatiles analysis package identifying volatiles and other potential resources in Lunar regolith, plus analysis of Lunar exosphere
  - **3 x L-DEPP**: dust environment and plasma package investigating dust motion, charge, size distribution, E-fields, plasma properties, radio environment
  - **AMERE** radiation biology experiment investigating effects on human cells
- Studies incorporate industry and scientists from outset
- Provide an important input for definition of interfaces between Lunar Lander and model payload
- Completion by mid 2012

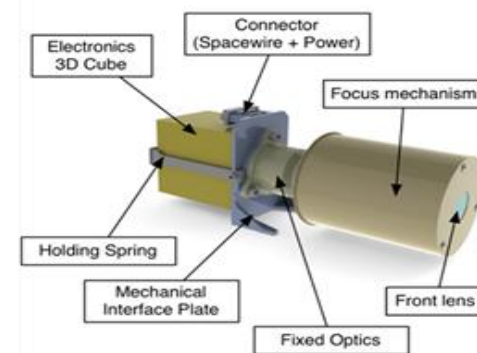
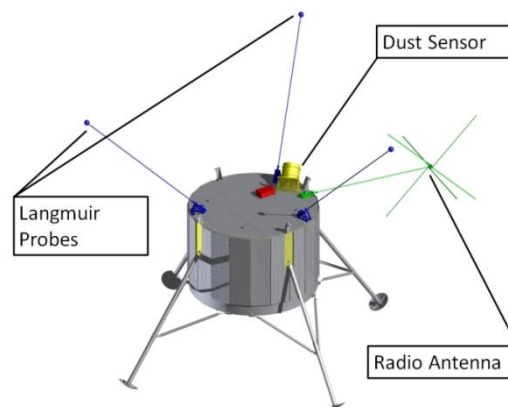
Separate study on a Mobile Payload Element (MPE) initiated by DLR and led by Kayser Threde ongoing  
DLR contribution in-kind to Lunar Lander



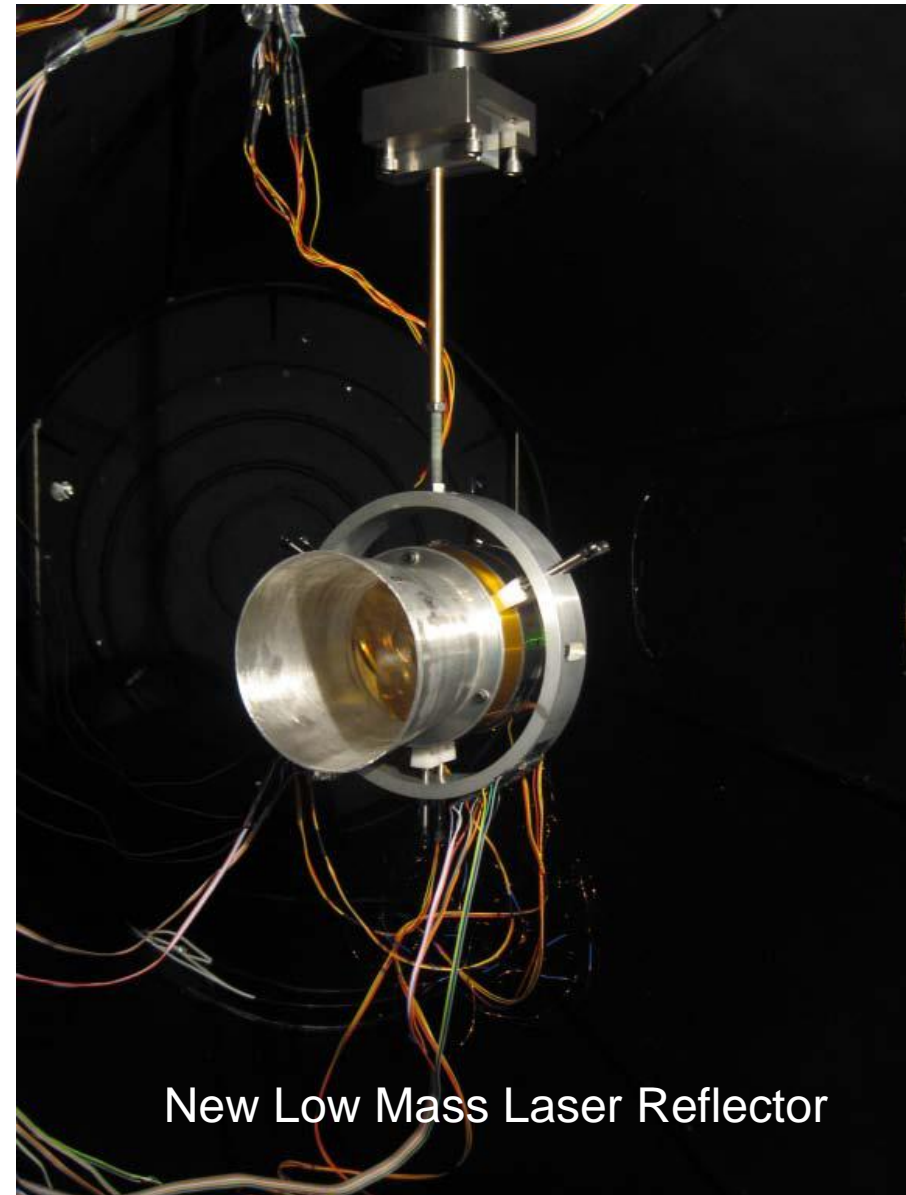
# Lunar Lander: Model Payload



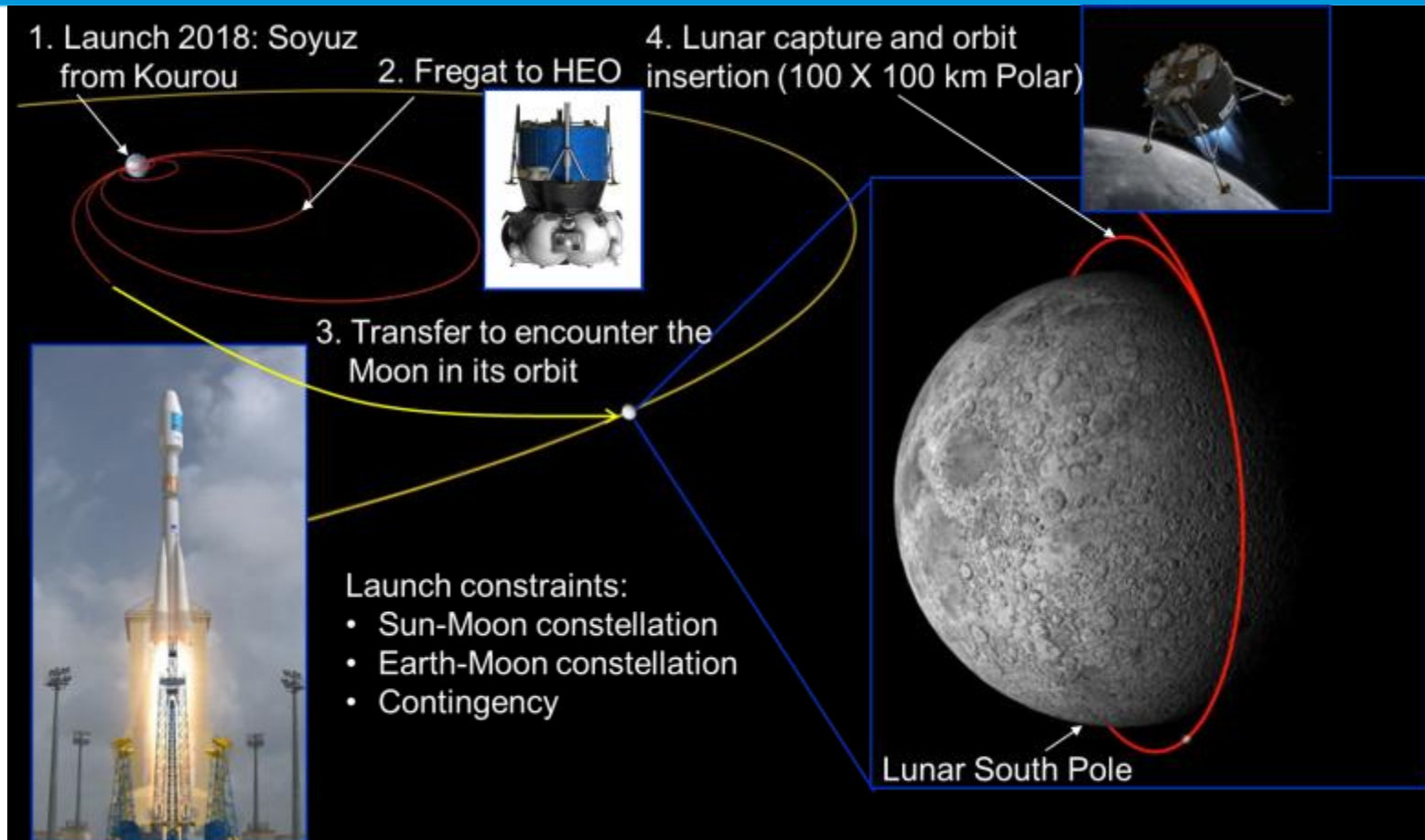
Package	Instrument
Lunar Camera Package (L-CAM)	Stereo Panoramic Camera
	High Resolution Camera
	Robotic Arm Camera
Lunar Dust Analysis Package (L-DAP)	AFM
	Micro Raman-LIBS
	Microscope
	External Raman-LIBS
Lunar Dust Environment and Plasma Package (L-DEPP)	Dust Sensor
	Langmuir Probes
	Radio Antenna
	Ion/Electron Spectrometer
	Magnetometer
Lunar Volatile Resource Analysis Package (L-VRAP)	Mass Sector Mass Spectrometer
	Ion trap mass spectrometer
Radiation and effects experiments	Radiation monitor



- ESA led Model Payload is not a selected payload
- Alternative experiments can be considered
  - Address exploration relevant questions
  - Provide fundamental scientific return
- E.g. Laser reflector
  - Verify landing precision
  - Provide absolute reference for lunar coordinate systems
  - lunar geodesy/geophysics
  - fundamental physics
- Supports exploration and science goals
- Strong Belgian science competence



# Mission Description: Launch to Lunar Orbit



Further to the initial trade offs in early Phase B1, the mission design has been stable for more than one year.



- **Phase B1 contract with EADS  
Astrium - Bremen started  
September 2010**
- **Current participating countries:  
Germany, Portugal, Canada, Spain,  
Belgium and Czech Republic.**
- **Payload accommodation studies in  
European Industries and Research  
Institutes (D, UK, NL, CH, S, B, PL, F,  
E, FN, CZ).**

## Lunar Lander Phase B1





# Lunar Lander Phase B1

 **Mission Prime**



Strong Belgian participation



- Software 
- Communication  
- Optical/electrical stimulator (navigation bread boarding) 

- Lunar Lander Phase A mission studied since 2008; Technology development since 2005.
- Mission architecture frozen, design stable since more than one year
- Project is ready to enter hardware development phase.

Soyuz Launcher



Technologies Activities

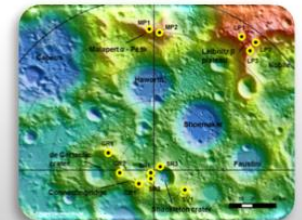
Landsafe



Landing System Development

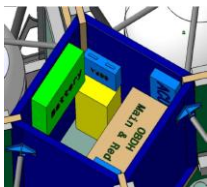
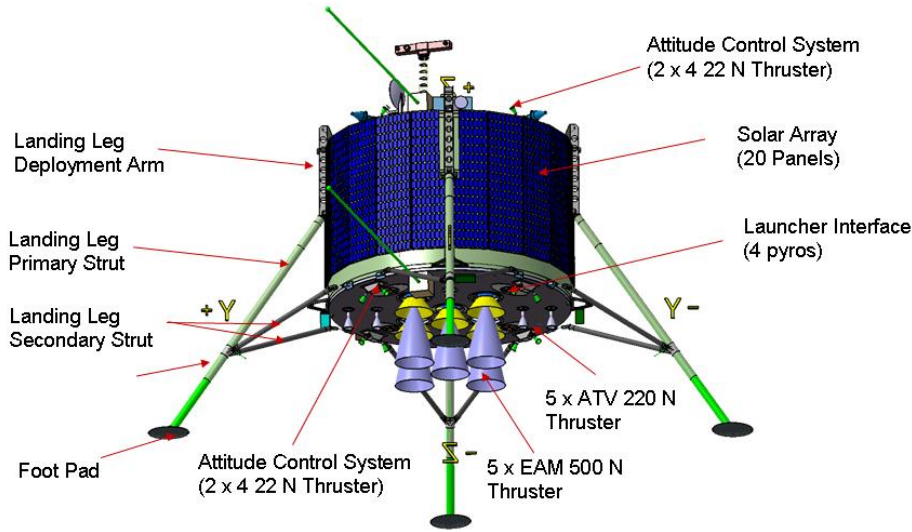


Landing Site Characterisation

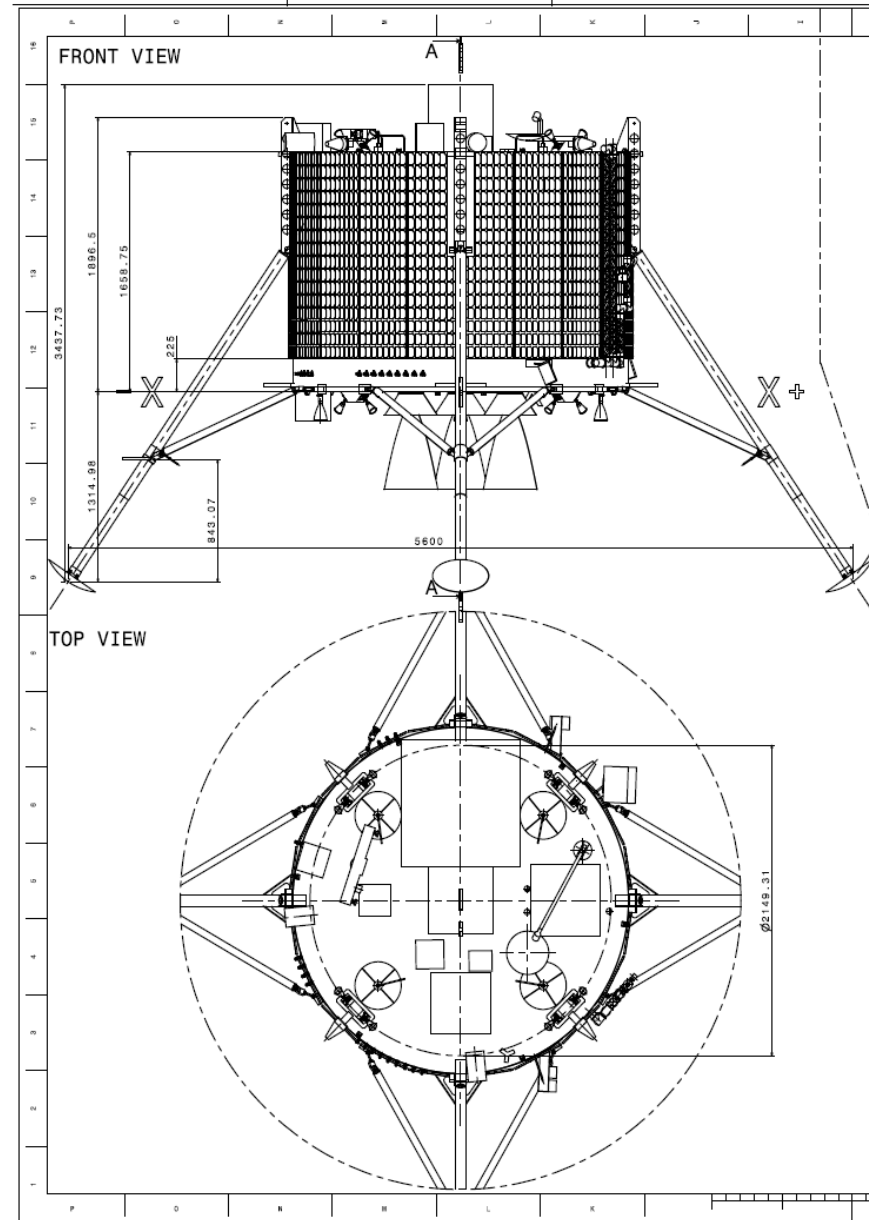
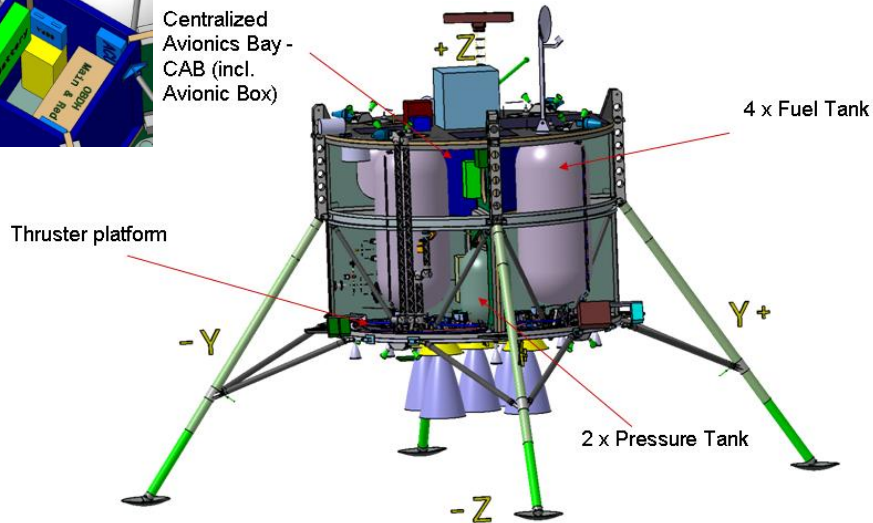




# Spacecraft Configuration



Centralized Avionics Bay - CAB (incl. Avionic Box)





# Subsystem / Equipment List

## Structure

- Main structure (top/bottom plates, struts, shear web)
- Secondary structure
- Payload servicing (manipulator arm, camera mast)
- Landing legs (primary/secondary strut, footpad)

## Power

- Solar generator (solar cells, panels)
- Power harness
- CAB (PCDU, battery, harness)

## Propulsion

- Propellant tanks
- Pressurant tanks
- 500N EAM engines
- 220N ATV engines
- 22 ACS engines
- Propulsion equipment (valves, pressure regulators, piping)

## Avionic Guidance Navigation and Control

- IMU
- Distance-to-ground sensor
- Lidar
- Navigation camera
- Sun sensors
- Star trackers
- Propulsion drive unit
- GNC Software

## Mechanisms

- Antenna deployment
- Antenna pointing
- Landing leg deployment and latching
- Camera mast deployment
- Camera mast pointing
- Manipulator arm joints

## On board Computer and Data Management

- Data Management System
- Data harness

## Thermal Control

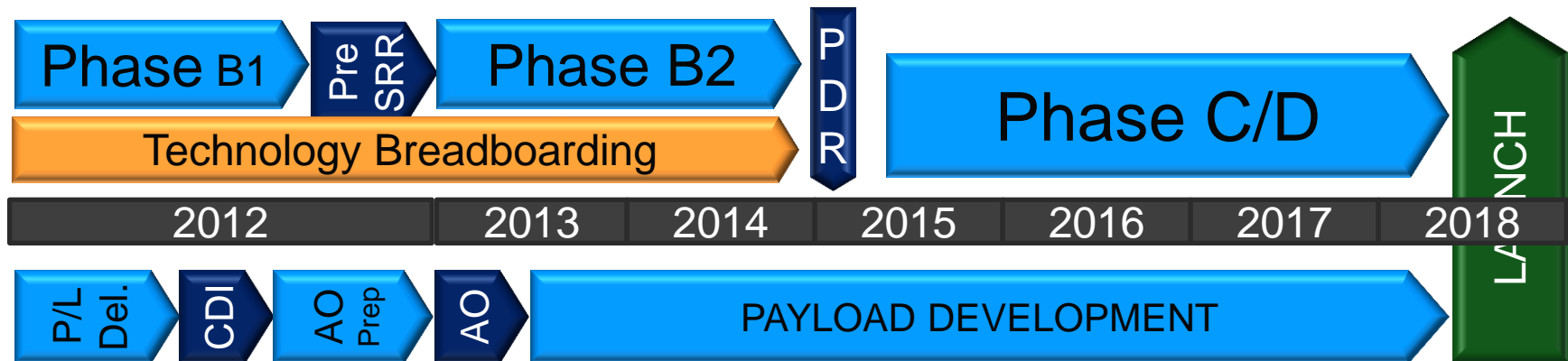
- MLI
- Heaters
- Sensors
- Thruster platform heat shield
- Radiators
- Loop heat pipes
- Heat switches

## TM/TC

- Transponder
- RF network
- High gain antenna
- Low gain antenna

# Schedule and Next Steps

- Pre-SRR in October 2012
- Ministerial Council in November 2012 (MC2012)
- S-PDR planned early 2015
- Bread boarding activities running continuously up to PDR (TRL 5)



- Call for Declarations of Interest (CDI) in May 2012, due 9 July 2012
- Announcement of Opportunity expected early 2013

- European Lunar Lander: frame to develop/apply Belgian industrial, research and scientific know-how with significant added-value
  - challenging, mass-critical mission (like any landing)
  - state-of-the-art technology and expertise required
- After Phase B1, pending approval at MC'12 , the industrial consortium will evolve, building on the existing consortium, but also adapting to new partners:
  - to broaden the industrial base and reflect the support across Europe
  - to further incorporate expertise necessary for B2/C/D/E
- Lunar Lander B2/C/D/E offers opportunities for design, manufacturing, verification, test, integration, operations and post-processing
- Phase B2 until PDR will be crucial: HW & SW breadboarding effort to be pursued in various areas (including at equipment level) to achieve TRL 5

# Areas of Possible Belgian Contributions

- Software
- Software verification facility
- Communications
- Tools for landing site certification
- Landing leg deployment/latching mechanism
- Thermal control assembly/component (e.g. loop heat pipe)
- PCDU
- MGSE, EGSE
- Trajectory reconstruction
  
- Scientific instrumentation
- Electrical ground support equipment for payload simulation / testing
  
- Others?





# Conclusions

- **The Lunar Lander is the culmination of several years of investment in design and technology development started with the Aurora Core.**
- **As an exploration mission gives the opportunity to develop advanced technology while providing new opportunities for Moon surface science.**
- **The spacecraft design is stable for more than one year. An intensive programme of bread boarding activities is coming to conclusion with very positive results.**
- **The Lunar Lander is a Project ready to go into a hardware development phase,**





# BACK-UP

human spaceflight



# Scientific Objectives

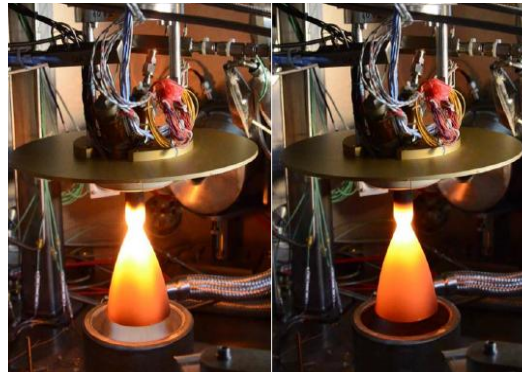
- Wide consultation to identify objectives and requirements

<b>Lunar Exploration Definition Team</b>
<b>Topical Teams and workshops:</b>
Dust Toxicity (T3LD)
Resources (TTELP)
Radiation Biology (TT-IBER)
Dusty Plasma Environments (TT-DPESS)
<b>Payload Definition Studies</b>
<b>Landing site characterisation studies</b>



- Workshop “Scientific Preparations for Lunar Exploration” at capacity with 180 participants
- Forthcoming special issue of Planetary and Space Science

- Propulsion:
  - Hot firing tests have established adequate behaviour and performance of 220N in pulse mode
  - Successful testing on a full breadboard of the propulsion feed system



220N engine hot-firing at various pulse frequencies

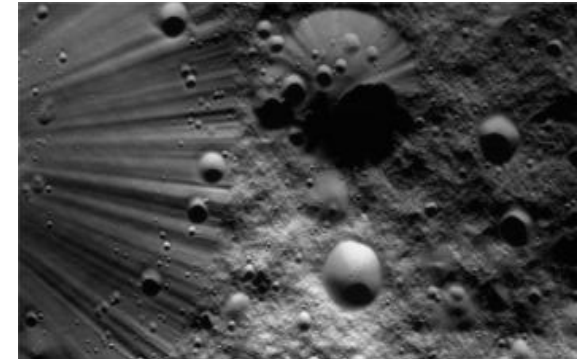


Propulsion feed system hydraulic mock-up used to investigate water-hammer effects, thruster cross-talk etc.

- GNC:
  - TRON facility at DLR Bremen shall be used to validate absolute visual navigation solutions, with HW in-the-loop testing



TRON facility at DLR-RY



Artificially generated terrain mock-up

+ avionics, Lidar, alternative Guidance & Control, landing legs (DLR/Astrium) etc.

# Industrial Team Phase B1



## Progress Meeting 6

Astrium Bremen, April 23rd/24th, 2012





# Ongoing Support Activities

## Payload Definition Studies

### L-DAP



### L-DEPP



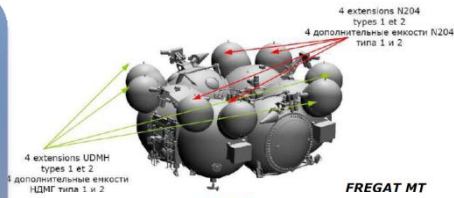
### L-VRAP



### Phase B1



## Soyuz Launcher Feasibility Assessment



## Landing Site Characterisation

